

IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

Applicants: Ishida et al.
Appl. No.: 09/646,849
Filed: October 17, 2000
Title:

"APPARATUS AND METHOD FOR JOINT MECHANISM, JOINT
APPARATUS, AND ROBOT DEVICE AND CONTROL METHOD
THEREOF"

Art Unit: 2837
Examiner: M. Fletcher
Docket No.: 113298-002

Assistant Commissioner for Patents
Washington, DC 20231

AMENDMENT

Sir:

In response to the Office Action dated August 29, 2001, please amend the above-
identified patent application as follows:

In the Drawings:

Please amend original Fig. 23 as per the attached Request for Approval of Drawing Changes.

In the Specification:

Please replace the paragraph beginning at page 2, line 19, with the following rewritten paragraph:

B' --With the conventional 2-leg walking robot, for example, as shown in Fig. 23, a main control unit (not shown) for controlling the operations of the entire robot is connected to each motor 3 (3-1 through 3-n) through a multi-axis controller 2, and the multi-axis controller 2 controls each motor 3 in each specific state at a control instruction output from the main control unit.--

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